

# Resource and Risk Management in Datacenters

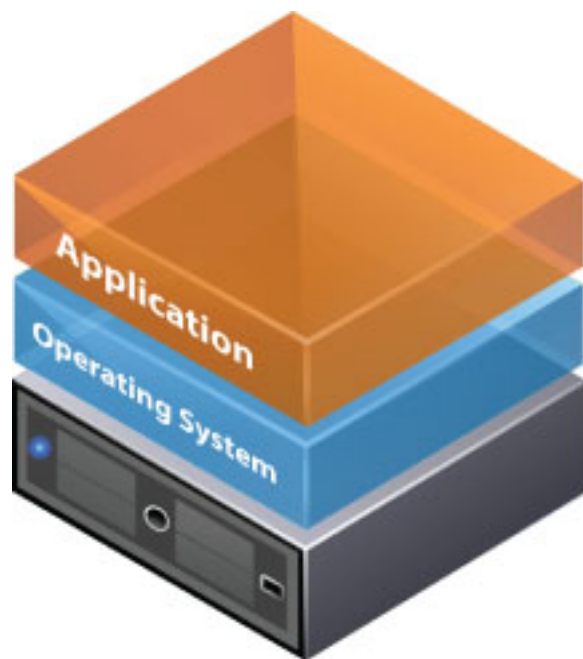
- Vincent van Beek
- Distributed Systems Group TU-Delft
- Supervisor: Prof. Dr. ir. Alexandru Iosup
- Promotor: Prof. Dr. ir. Dick Epema



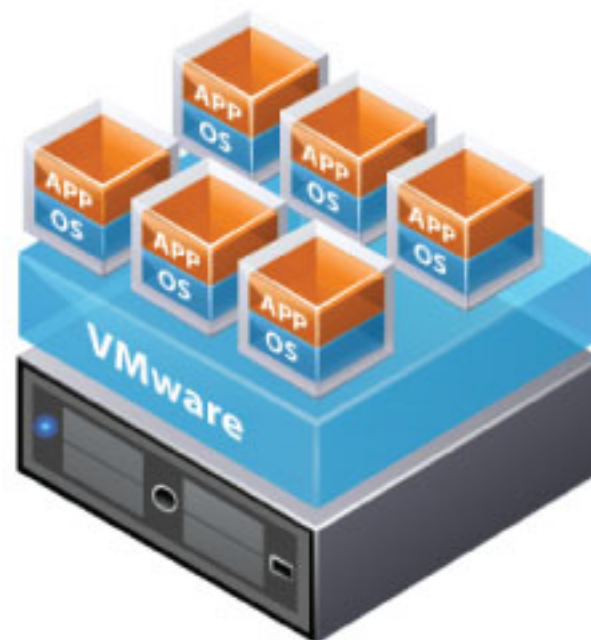
# Why Resource and Risk Management in Datacenters

- **Datacenters are at the center of all IT systems**
- **Hosting Business Critical Applications**
- **New technology is introduced at a rapid rate**
- **Consolidation is driving costs down**
- **Many enterprise customers are risk averse and want guarantees**

## Virtualization in Datacenters

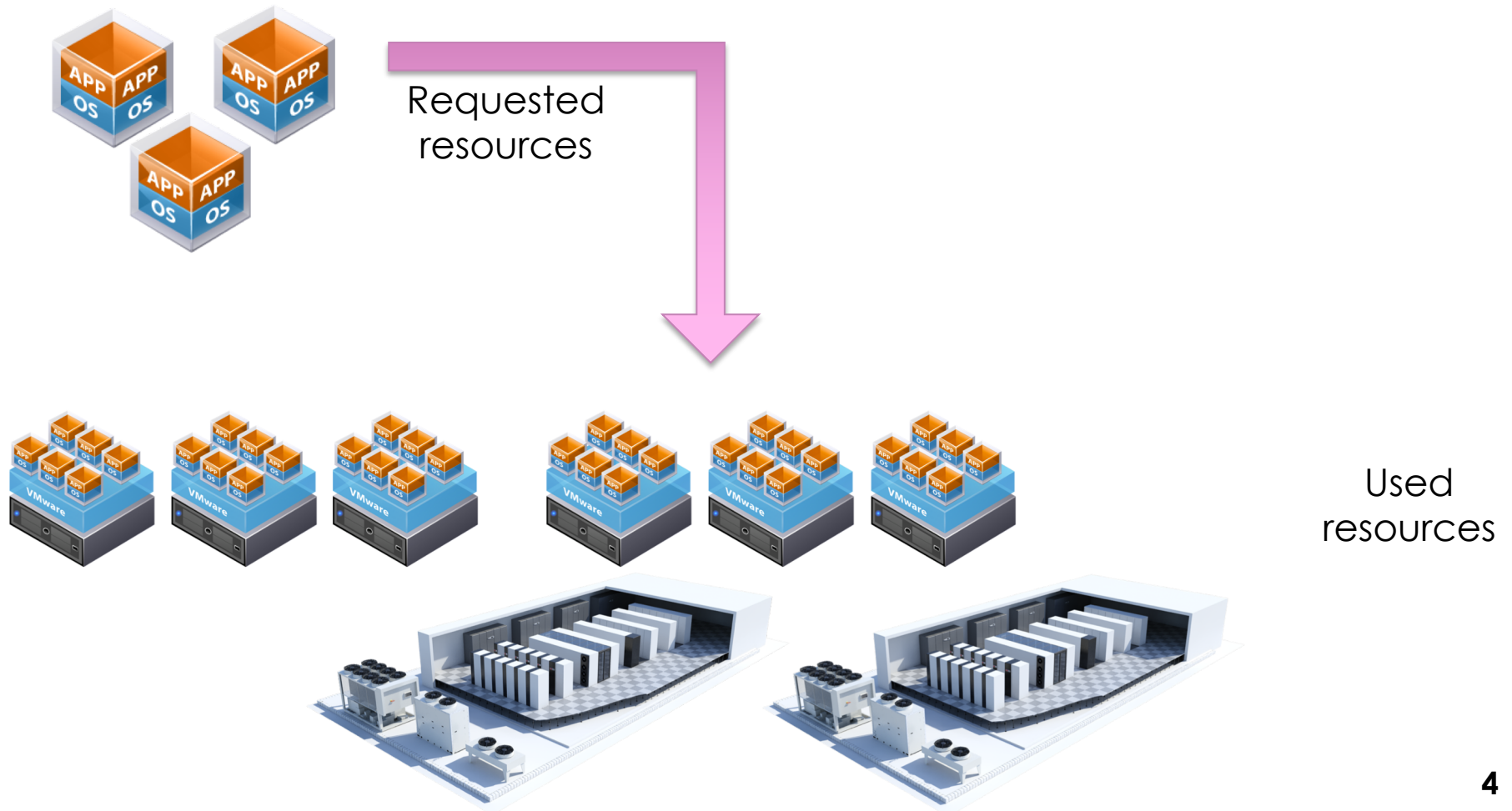


Traditional Architecture



Virtual Architecture

# VM Placement



## Problem statement

Affinity

SLAs

Dynamic Characteristics

Multiple Resources

## Where to put which VM?

Time Component

Many Single Resource Solutions

Scheduling

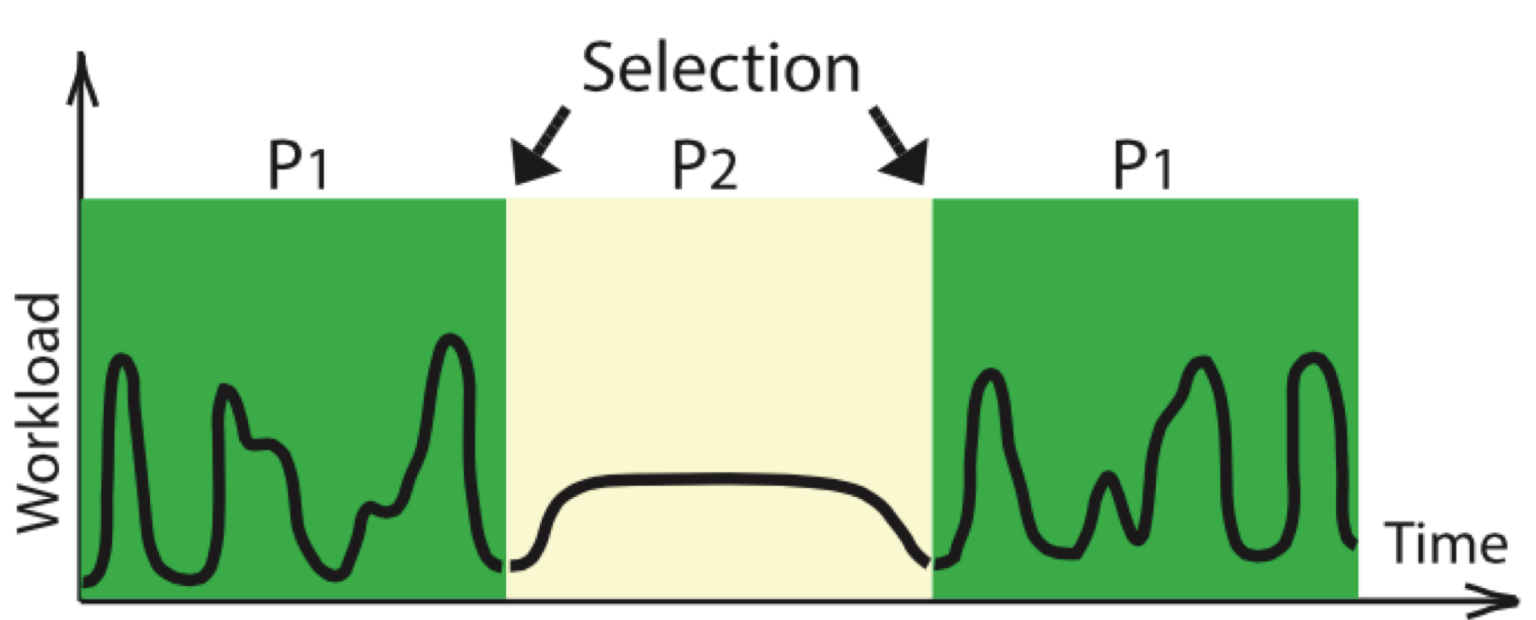
Workloads

Many Point Solutions

Anti-Affinity

BlackBox Problem

## Why Portfolio Scheduling



Source: Deng et al. A periodic portfolio scheduler for scientific computing in the data center

## What is Portfolio Scheduling?

Which policies to  
include?

**Creation**

Which policy to activate?  
**Explain to sysadmin**

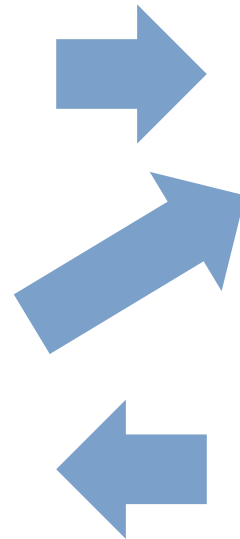
**Selection**

**Reflection**

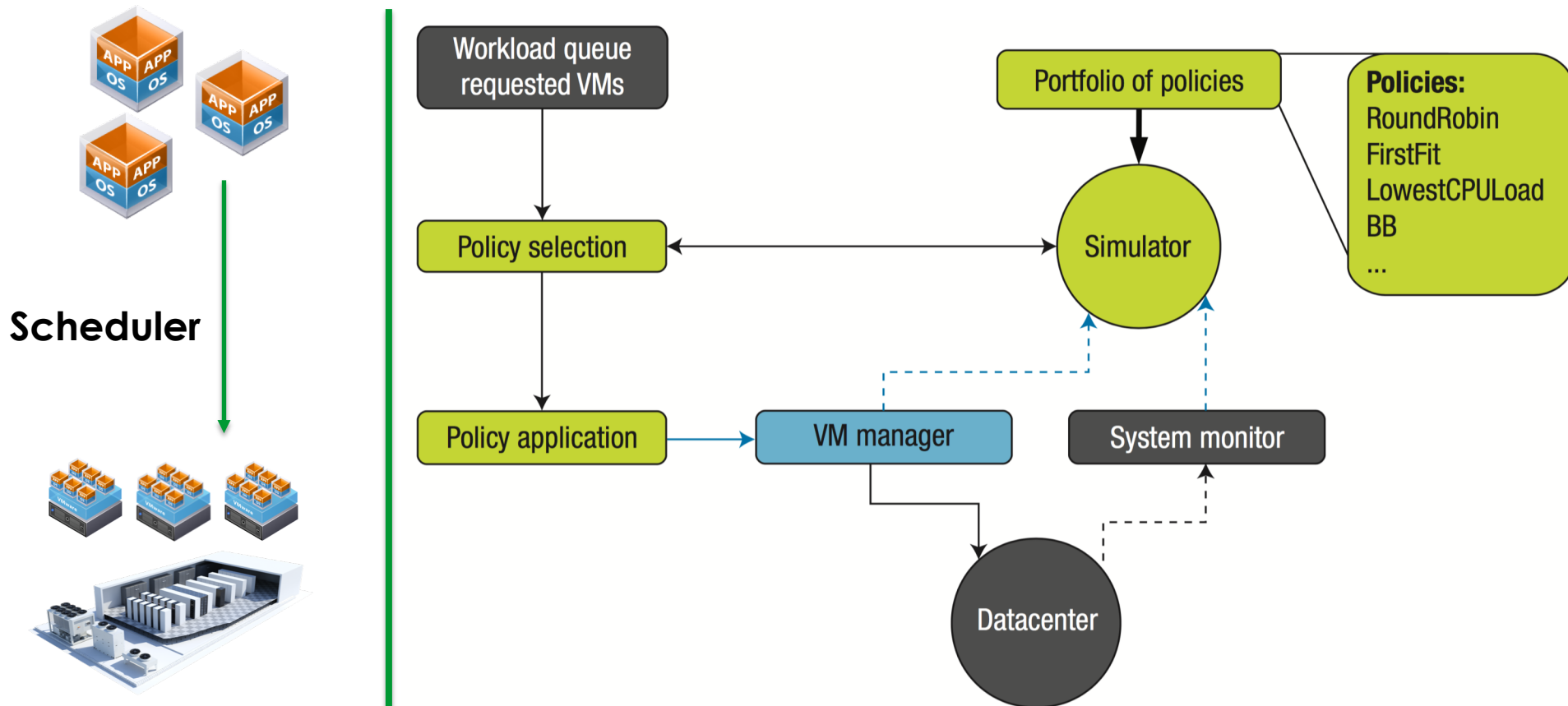
Which changes to the  
portfolio?

**Application**

**Validate selection  
immediately**

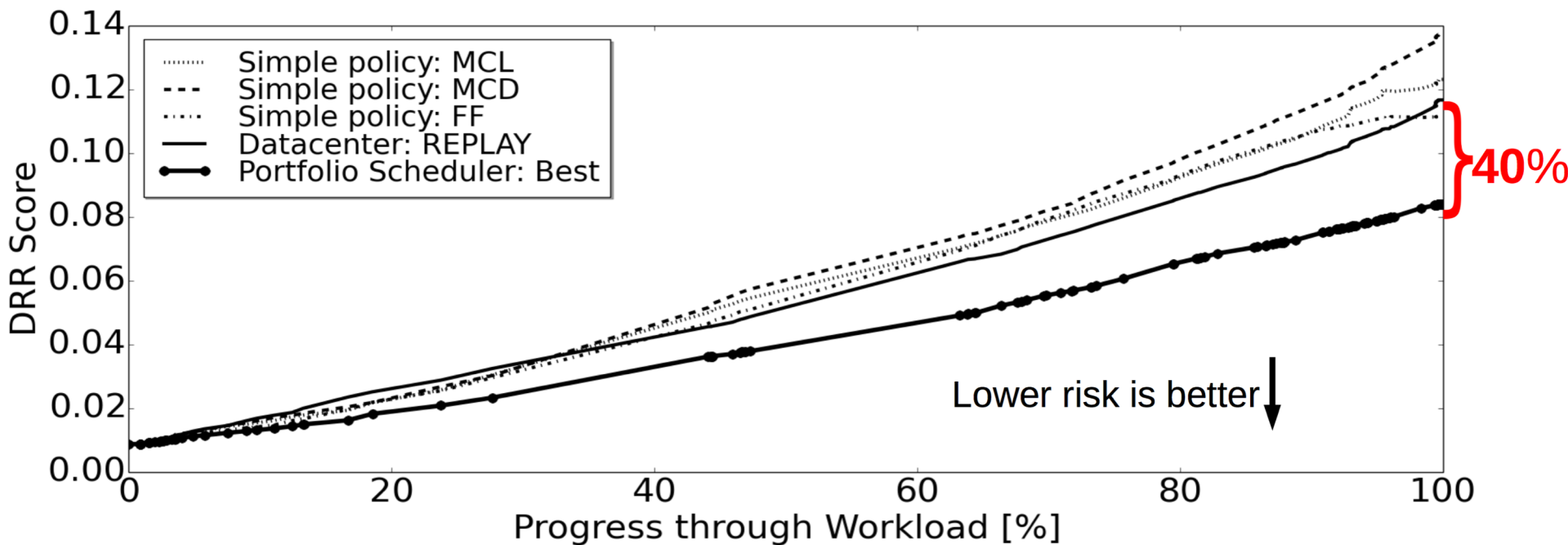


# Portfolio Scheduling for VM placement In Datacenters



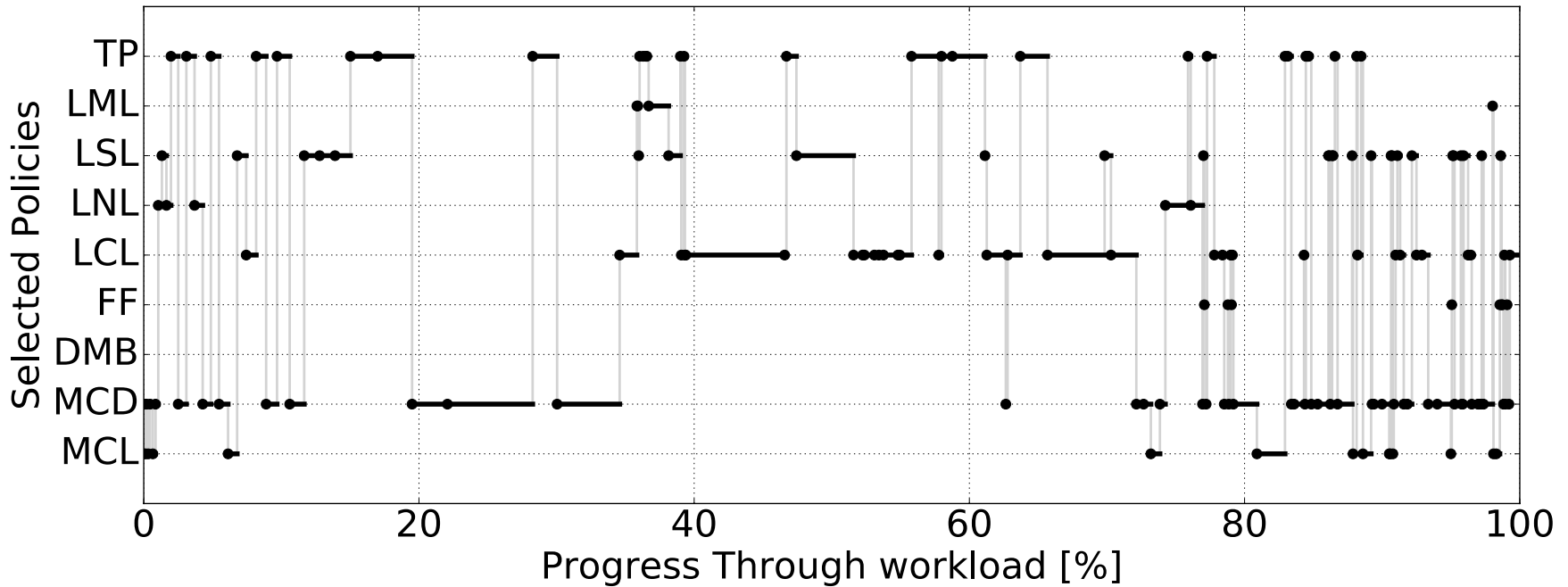


## PS vs its constituent policies



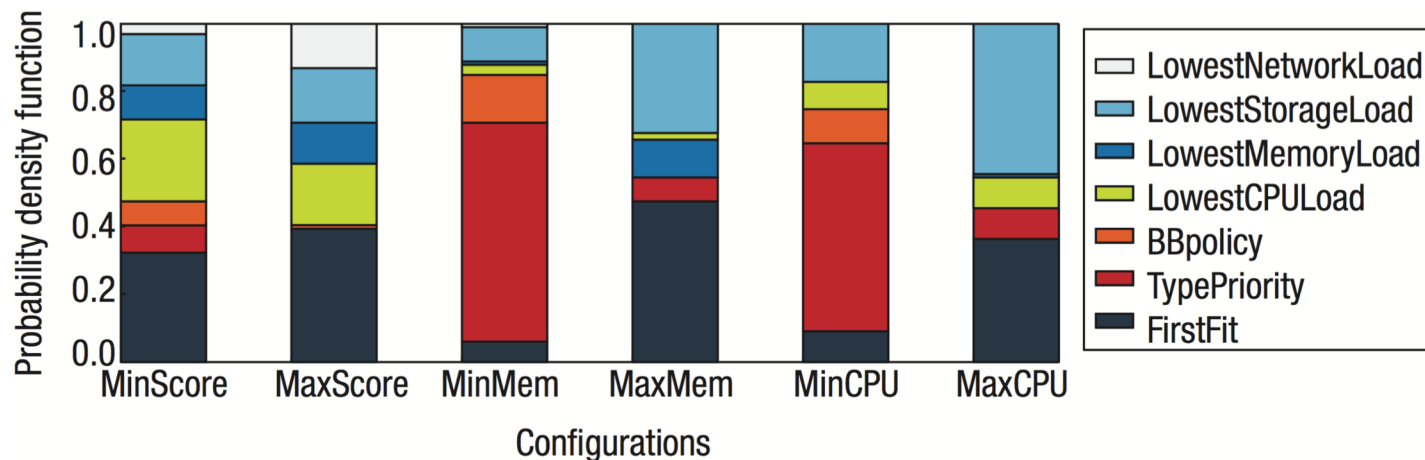
1. Portfolio scheduler achieves the lowest risk of all scenarios.
2. Portfolio scheduler achieves at least **35%** lower DRR compared to individual policies.
3. **40%** lower DRR than commercial production system (REPLAY).

# Policy Selection over Time



# Portfolio Scheduling for Business-Critical Workloads

- Policy selection for 6 different utility functions



# Roadmap

## Near future

- Implementation of Portfolio Scheduling in OpenDC
- SLA based scheduling

## Long term

- Multi Cloud
- Reflection
- Theoretic Boundaries
- Practical Limitations

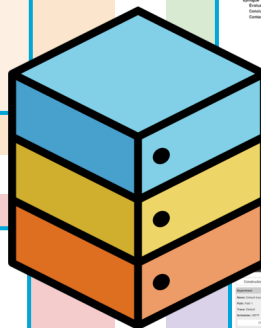
# What does OpenDC bring to the table?

## 1. Datacenter Technology & Methods

Risk Analysis +  
Management

Efficiency →  
SME  
Availability

Heterogeneity



## 3. Education Practices



Robotics Course Cloud Assignment

Using OpenDC to understand how your robot's code runs in a distributed environment.

Learning goals. As this assignment you will have seen about:

- The distributed system architecture and the design of distributed systems.
- Identify and use the concepts of their generation of distributed systems in a distributed environment.
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Table of Contents

1. What do you notice about the temporal distribution and size of the tasks in the "image processing" workload? How do these tasks map to "spatial stages of doing a panoramic scan with a robot's camera?"

2. What do you notice about the temporal distribution and size of the tasks in the "path planning" workload? How do these tasks map to logical stages of pre-computing from abstract goals to an environment of known robots at once, and then processing each robot's localization data on each step and one of those abstract goals to follow?

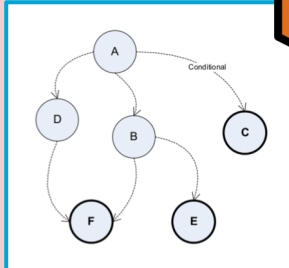
3. If you were designing a scheduler with the aim of completing the entire workload as quickly as possible, how would you distribute tasks for the "image processing" workload? For the "path planning" workload?

Mnemos: Self-Expressive Management of Business-Critical Workloads in Virtualized Datacenters

Vincent van Beek<sup>1,2</sup> Jesse Donkervliet Tim Hegeman  
Stefan Hugtenburg  
Alexandru Iosup

<sup>1</sup> Bitbrains IT Services Inc., Amstelveen, the Netherlands  
<sup>2</sup> Delft University of Technology, Delft, the Netherlands  
Corresponding author: [vincent.vanbeek@bitbrains.nl](mailto:vincent.vanbeek@bitbrains.nl)

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## 2. Scientific Methods

## 4. Software & Data Artifacts

## Take home message

**Datacenter research is important!**

**Ask members of the @large team about OpenDC**

**<https://opendc.org>**